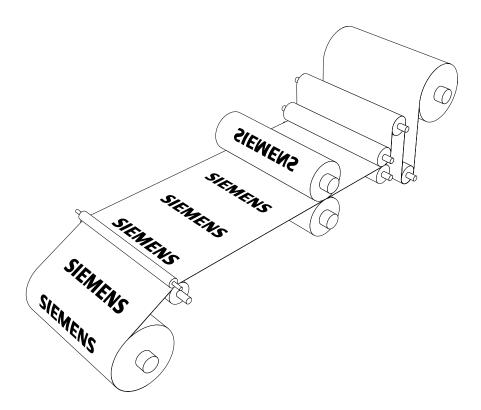
### **Applications**

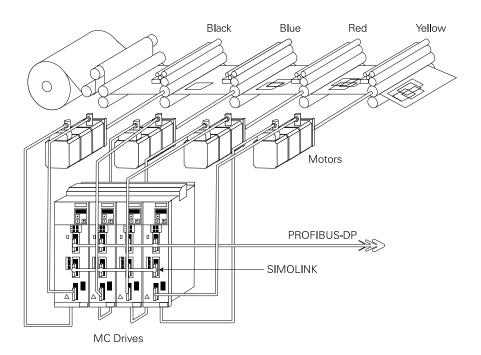
There are any number of applications where motion control can be utilized. The features and functions of the MASTERDRIVE MC product line provides appropriate solutions for these application requirements. Choosing the right components can be confusing and takes careful thought and planning. As you have seen throughout this book there are a number of servomotors, encoders, drives, and technology options to chose from. The following application examples, along with the selection flow chart in the next section, will help you in the planning process. There are, of course, many applications other than the ones illustrated in this section appropriate for the MASTERDRIVE MC.



### **Offset Printing**

Offset printing traditionally uses a mechanical line shaft to synchronize the different color print stations. The mechanical devices involved require high maintenace, and the system is limited in speed.

The mechanical line shaft system can be replaced with individual servomotors which are precisely synchronized through the MASTERDRIVE MC and SIMOLINK. Communication to higher level controls, such as a SIMATIC S7 PLC, for evaluation of system status and drive setpoint signals, is accomplished with PROFIBUS-DP.

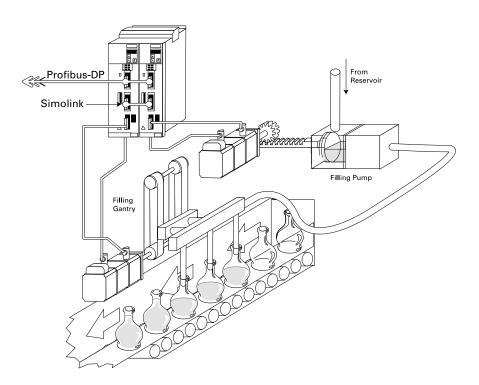


Application Requirement	Web Handling with Synchronization
MASTERDRIVE MC Feature	Synchronization: Virtual Master, Real Master, Gear Box (Electronic Line Shaft)
MASTERDRIVE MC Solution/Benefit	Increased Accuracy and Production Print Speed. Flexibility to Add and Remove Print Stations with Minimum Downtime.

#### **Bottle Filling**

Some bottle filling applications, such as cosmetics, require the distance between the filling pipe and the liquid level in the bottle to be kept constant. In addition, the filling pump must maintain a constant flow. These two axes can be precisely synchronized with the MASTERDRIVE MC.

In this application, the pump drive acts as the master and the filling gantry acts as the slave. As the pump provides a constant flow of product, the filling gantry movement is synchronized, through a cam profile that corresponds to the bottle contour. This maintains a constant filling pipe to liquid distance.

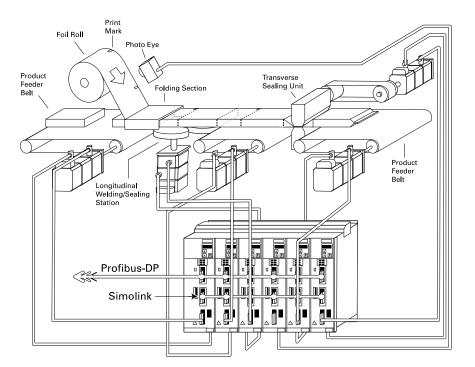


Application Requirement	2-Axis Synchronized Control		
MASTERDRIVE MC Feature	Synchronization with Cam Profiling		
MASTERDRIVE MC Solution/Benefit	Quick Cam Profile Change to Accommodate Bottle Contour Change. Increased Production for Multi-Product Line Runs.		

### Horizontal Bagging

This application involves a continuous roll of foil for horizontal bagging. The sealing station handles the foil transport. Electronic line shaft and print mark registration ensure the foil is synchronized with the products being packaged. Electronic line shafting also ensures the product feeder belt and the foil are in continuous position synchronization. Print mark registration will accelerate or decelerate the foil to make up for possible stretch. This ensures that printed labels on the foil will be correctly positioned on the package.

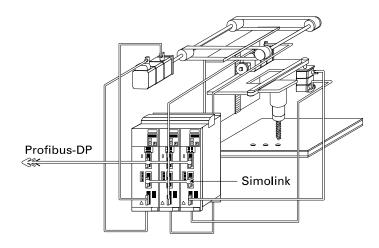
The transverse sealing station must travel with the line in order to achieve continuous packaging. This is accomplished with the MASTERDRIVE MC's electronic line shaft and electronic cam functions. The sealing station is accelerted with the electronic line shaft function to the speed of the product (x-axis). The electronic cam function closes the sealing jaws (y-axis) while the sealer moves across and simultaneously seals the package.



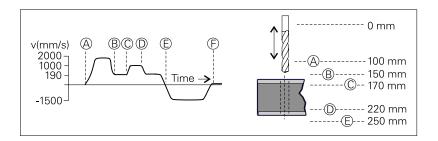
Application Requirement	Continous Positioning and Synchronization. Continuous Packaging		
MASTERDRIVE MC Feature	Print Mark Registration Synchronization: Electronic Line Shaft Control Including Cam Profile		
MASTERDRIVE MC Solution/Benefit	Continous Adjustment to Compensate for Foil Stretch. Multi-Axis Coordination for Sealing and Bagging Sections.		

### Composite Drilling

Positioning the x- and y-axis to locate the drilling tool can be accomplished with the manual data input (MDI) mode. Once the drilling tool has reached the desired location, the automatic function takes over and controls the movement of the z-axis. The following instruction set is an example of a drilling profile.



- Moving from A to B the drilling gantry rapidly traverses to just in front of the board and starts to reduce the feed velocity.
- At point B the drill reaches the reduced feed velocity to drill through a plastic laminate.
- Moving from B to C the drill slows to drill through the laminate.
- Moving from C to D the drill increases to normal velocity to drill through core.
- Moving from D to E the drill reduces velocity to drill through bottom laminate.
- Moving from E to F the drill returns with increased velocity.

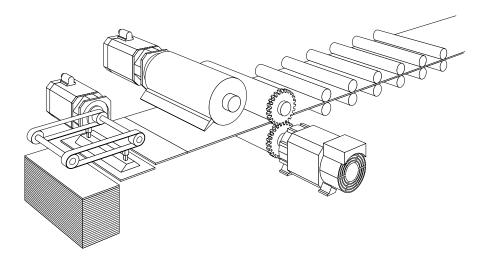


Application Requirement	3-Axis Positioning (Composite Drilling).
MASTERDRIVE MC Feature	MDI Point-to-Point Positioning. Automatic Mode Positioning.
MASTERDRIVE MC Solution/Benefit	High Accuracy Drill Bit Placement and Optimized Drilling Speed to Improve Quality of Cut and Tool Life.

#### Cut to Length Rotary Knife/Sheater

In Cut to Length applications, the purpose is to cut material to a precise length. For a fixed cut length, and a knife circumference of the same length, it is simply a matter of maintaining a constant speed between the web and the knife. However, for products that require various cut lengths, the knife's circumference would have to vary to match these new cut lengths. Since this would not be practical, the knife speed is often profiled. By varying the knife speed various cut lengths can be obtained. Furthermore, the rotary knife is accelerated so that as the cutting edge comes into contact with the material it is traveling at the same velocity. This is done to avoid "ripping" the material.

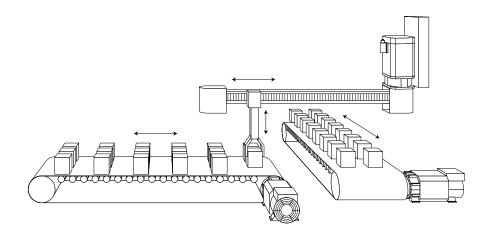
To accomplish this task a Cam profile is often employed. Using the technology features of the MASTERDRIVES MC, a number of cam profiles can be created to perform the needed contoured movement that is synchronized with the material to perform the cut.



Application Requirement	Variable Speed and Product Cut Lengths.		
MASTERDRIVE MC Feature	Synchronization with Cam Profiling		
MASTERDRIVE MC Solution/Benefit	Short Current Rise Time allows for High Dynamic Response. Multiple Cam Profiles Allow for Quick Changeover to Various Product Lengths.		

#### **Pick and Place**

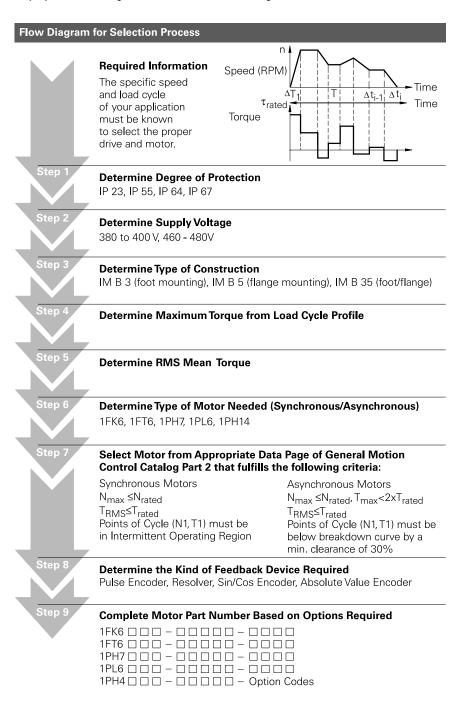
Pick and Place applications involve the precise movement of product from one location to another. Using the Point-to-Point positioning features (MDI mode) of the MASTERDRIVES MC, this precise movement can be realized. Typically the gripper claw is "homed" to the starting location during initialization of the system. From that point, as product is sensed, the gripper closes on it and the Point-to-Point move is made. Once the final destination point is reached the gripper releases the product and the return move to home position is carried out. SIMOLINK is the perfect choice to coordinate these actions. It allows for easily sending all of the appropriate status and control signals from one axis drive to the next.



Application Requirement	Pick and Place Positioning
MASTERDRIVE MC Feature	MDI Point-to-Point Positioning
MASTERDRIVE MC Solution/Benefit	High Accuracy Organization and Location of Product Packaging

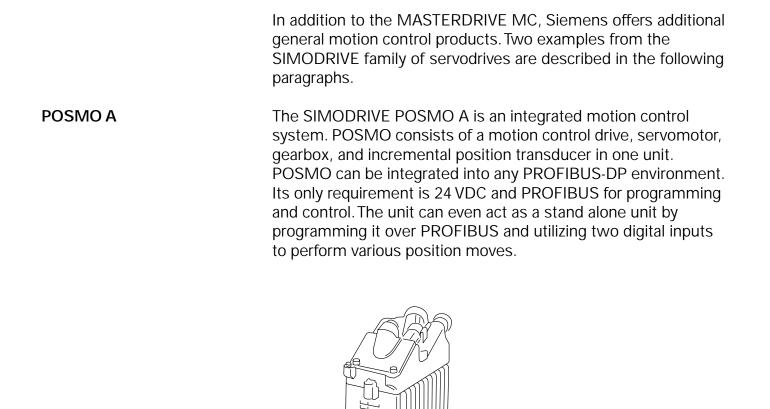
## Selection

The following flow diagram, along with Part 1 and Part 2 of the General Motion Control Catalog, will help you select the right equipment for your motion control system.



Step 10	Determine Length and Size of Prefabricated Power Cable Required or Determine Size of Coupling for Customer Assembly
	Power Cable Order Number:
Step 11	Determine Length and Size of Prefabricated Signal Cable Required or Determine Size of Coupling for Customer Assembly Encoder/Resolver Cable Order Number:
Step 12	If Standard Overload (160% for 30 s during 300 s load cvcle)
	Select Converter/Inverter that Corresponds to the Chosen Motor from the Motor Data Based on Standard Overload Conditions
Ct	Skip to Step 15
Step 13	If Above Standard Overload
	If Higher Overload Time and Overload Percentage is Needed go to General Motion Control Catalog Part 1 MASTERDRIVES MC Determine I <sub>motor max</sub> and I <sub>RMS</sub>
Step 14	Determine Whether an AC - AC or DC - AC Unit and "Form Factor" is Needed
	AC - AC: Typical Single Axis System DC - AC: Typical Multi-Axis System (Rectifier Required)
Step 15	Select Converter/Inverter that Fulfills Overload Requirements
	$\begin{array}{l} I_{RMS} < I_{Un} \text{ in 300 s Cycle Time} \\ I_{max} < 1.6 \times I_{Un} \text{ for 30 s in a 300 s Cycle Time (Compact/Chassis Units)} \\ \text{or } I_{max} < I_{Un} \text{ for 250 ms in a 1 s Cycle Time (Compact PLUS Units)} \end{array}$
	Drive Order Number:
Step 16	Select Rectifier
Step 17	Determine Feedback Options for Drive
	SBP, SBR 1/2, SBM
	Feedback Board Order Number:
Step 18	Determine if Communication Board is Required
	PROFIBUS - CBD, SIMOLINK - SLB
	Communication Board Order Number:
Step 19	Determine if Additional Input/Output is Required
	Expansion Board EB1 or EB2
	Expansion Board Order Number:
Step 20	Determine if Optional Technology Functions are Required
	Software or Technology Board Order Number:
Step 21	Determine if Additional Options such as Line Reactors, OP1S, RFI Filters, Capacitor Modules, etc. are Required
Step 22	Determine Enclosure Needed

## SIMODRIVE



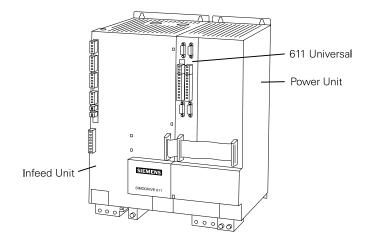
**POSMO** Data

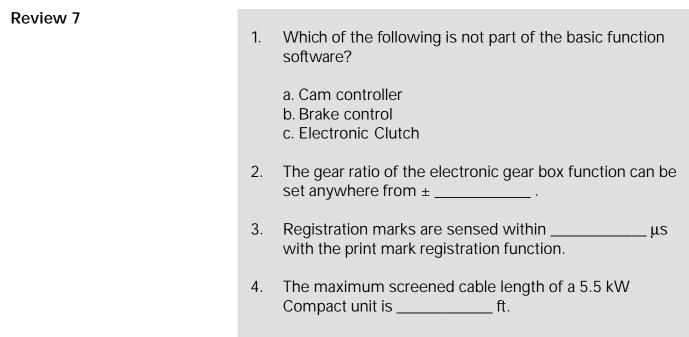
Degree of Protection Voltage Power Gear Drive

IP54 24 VDC ±20% 62 W 4.5:1 to 162:1

#### SIMODRIVE 611 Universal

The SIMODRIVE 611 Universal is a closed-loop control plug-in unit. The 611 Universal is made up of an infeed module and a power module. The infeed module contains a complete electronics power supply and is used to convert the incoming AC line (400 to 480 VAC) to DC. The power module houses the 611 Universal and provides the output to the servomotor. The 611 Universal will support 1 or 2 axis. Like the POSMO, the SIMODRIVE 611 Universal can be integrated into any PROFIBUS -DP environment. This drive is rated from 3 - 250 amps. It is designed for positioning tasks and can operate both sinewave servomotors and linear motors.





5. When selecting a motion control system the speed and \_\_\_\_\_ load cycles must be known.

# **Review Answers**

Review 1	1) MASTERDRIVE; 2) linear, rotational; 3) h.
Review 2	1) force; 2) 5 N; 3) torque; 4) 6; 5) inertia; 6) 1:1; 7) Work; 8) torque, power; 9) SimoSize.
Review 3	1) synchronous, asynchronous; 2) 120; 3) synchronous; 4) slip; 5) b; 6) 105; 7) 64.
Review 4	1) S1; 2) 10; 3) continuous, intermittent; 4) 81; 5) asynchronous.
Review 5	1) asynchronous; 2) 4096; 3) II, IV; 4) ACTIVE FRONT END
Review 6	1) 37; 2) X1; 3) 100; 4) C; 5) CBP; 6) converter; 7) LBA.
Review 7	1) C; 2) 32,767:32,767; 3) 1; 4) 164; 5) torque

# Final Exam

	The final exam is intended to be a learning tool. The book may be used during the exam. A tear-out answer sheet is provided. After completing the test, mail the answer sheet in for grading. A grade of 70% or better is passing. Upon successful completion of the test a certificate will be issued.				
Questions	1.	is a twisting or turning force that causes an object to rotate.			ning force that causes
		a. b.	Torque Friction	c. d.	
	2.	-	y it is desirable to ha een the load and the		
		a. b.	1:2 1:1	c. d.	2:1 2:2
	3.	3. The torque required to accelerate a system with a tota inertia of 0.010 kgm <sup>2</sup> from rest to 2500 RPM in 0.1 seconds is Nm.			
		a. b.	7.85 13.08	c. d.	26.17 32.56
	4.	is a Siemens PC program designed to accelerate the process of calculating speed, torque, and inertia of a motion control system.			ting speed, torque,
		a. b.	SIMOLINK PROFIBUS-DP	c. d.	SimoSize POSMO
	5.	The maximum temperature rise of a motor with Class F insulation, not including the margin for a hot spot, is K.			
		a. b.	80 125	c. d.	130 105

6.	A motor with an enclosure that protects against dust and water jets would be classified as IP				
	a. b.	23 55	c. d.	68 65	
7.		is a duty cy mittent period withou		ich operates for an ing between cycles.	
	a. b.	S1 S3	c. d.	S2 S4	
8.	Winc	ling version	is	s rated for 6000 RPM.	
	a. b.	A G	c. d.	F K	
9.		ange of rated torque	of a 1	PH7 motor is	
		22 - 1145 0.8 - 16.5	c. d.	370 - 1720 34 - 78	
10.	and u	The encoder has 8192 coded positions and uses a mechanical gear sequence to count up to 4096 revolutions.			
	a. b. c. d.	Rod 431 ERN 1381 ERN 1387 EQN 1325			
11.	is a method of braking which uses IGBTs in the converter section and provides sinusoidal regen current back to the incoming power supply.				
	a. b. c. d.	5	itive Fr raking	ont End	
12.	The maximum kW rating of a Compact PLUS dirve is kW.				
	a. b.	15 22	c. d.	18.5 37	

13.		Compact PLUS has _ rectional inputs and c		programmable
	a. b.	two three	c. d.	four six
14.		o optic Compact PLUS.	n board	ds can be installed in
	a. b.	two three	c. d.	four six
15.	cosir	is an encoc ne encoders as well a		rd used for sine/ plute value encoders.
	a. d.	SPB SBR2	c. d.	SBR1 SBM
16.	supp	refers to a solution in the second sec		in which one rectifier C inverters.
	a. b.	Multi-Axis SIMOLINK	c. d.	PROFIBUS-DP Common Bus
17.	in the			ot for an encoder board , and Chassis drives.
	a. b.	A B	C. d.	C D
18.	The (	Cam controller is par	t of the	·
	a. b. c. d.	basic function soft rotary axis functior linear axis functior Roll feed function	า	
19.		maximum length of a kW converter is		
	a. b.	35 50	c. d.	65 70

20. \_\_\_\_\_ is a type of motion control drive that has an integrated motion control drive, servomotor, gear box, and incremental position transducer is one unit.

- a. SIMODRIVE 611 Universal
- b. POSMO
- c. Compact PLUS
- d. PROFIBUS-DP

Notes