SIMATIC S7-1200 G2

Smart choice for basic automation

FESTO VTUX



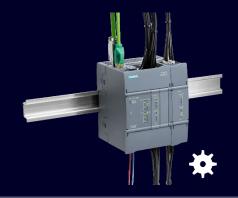


Overview

Highlights of SIMATIC S7-1200 G2









Enhanced performance & scalability

- Enhanced processing power, dedicated communication performance and more memory
- Up to 31 PROFINET devices and synchronized program execution with PROFINET IRT
- Optimized scalable hardware portfolio and seamless scalability across all SIMATIC controllers
- Analysis and optimization of PLC runtime via code with Profiling

Flexible machine safety

- Fail-safe integrated in the complete range (PROFIsafe communication, I/Os)
- Improved F-IO Portfolio with F-SBs and mixed I/O modules
- Fail-safe engineering integrated in STEP 7 Basic

Efficient motion control

- Control of single axes, coordinated axes and simple kinematics
- Integrated motion control technology objects simplifying configuration















Increased data transparency

- Near Field Communication (NFC) for wireless access to diagnostic, operational and device data
- Web API as an interface for reading and writing CPU data

i Scalable, cost-optimized and powerful portfolio for the basic automation segment

OverviewCPUs and communication

	CPU 1212(F)C	CPU 1214(F)C			
RAM Data	500 k	750 k			
RAM Progr.	150/200 k	250/300 k			
Retentive Memory	20 kB	20 kB			
Bit performance	37 ns	37 ns			
W x H x D (mm)	70 x 125 x 100	80 x 125 x 100			
Integrated DI/DO	8/6	14/10			
PROFINET/Modbus TCP	2 ports IRT	2 ports IRT			
Communication Modules	3 max	3 max			
Total SMs + CMs	6 max	10 max			
High-Speed Counter	8	8			
Total SBs	1 max	2 max			
Position axes Typical ¹ Maximum ²	4 10	4 10			
Motion Control (MC) Resources ³	800	800			
Extended MC Resources ⁴	40	40			
NFC	✓	✓			
SIMATIC Memory card	Optional	Optional			
Variants	DC/DC/DC & DC/DC/RLY & AC/DC/RLY (Std. only)				

Communication

CB 1241

RS485

CM 1241

PtP (RS232/RS485/RS422)



¹ At 4 ms Servo/IPO cycle time and 35% CPU load due to Motion Control. Estimated values are subject to implementation of use case I 2 No further TOs applicable

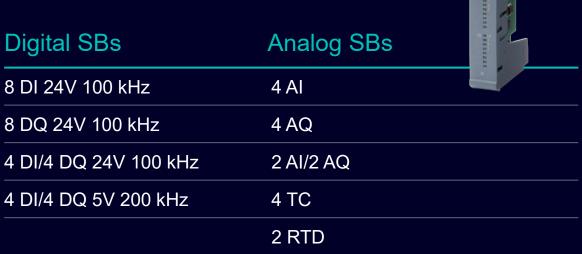
³ Resources for Motion Control technology objects: Speed axis = 40 | Positioning axis = 80 | Synchr. Axis = 160 | Output cam = 20 | Output cam track = 160 | Measuring input = 40 | Ext. Encoder = 80

⁴ Resources for Extended Motion Control technology objects: Cams (1,000 points and 50 segments) = 2 | Cams (10,000 points and 50 segments) = 20 | Kinematic objects = 30 | Interpreter = 60 | Leading axis proxy = 3

Overview

Signal boards and signal modules

SBs



SMs

Digital SMs	Analog SMs	60 A
DI 16 x 24 V DC	8 AI	
DQ 16 x 24 V DC 0.5 A	8 AQ	
DQ 16 x Relay	4 AI/4 AQ	
8 DI/8 DQ	8 AI TC	
8 DI/8 RLY	4 AI RTD	

Overview

Fail-safe: signal boards and signal modules

SBs	SMs
4x F-DI(1001)/2x F-DI(1002), 4-Vs ¹	8x F-DI(1001)/4x F-DI(1002), 8-Vs ¹
2x F-DQ, PP-PM ¹	4x F-DQ, PP-PM ¹
2x F-DI(1001)/1x F-DI (1002), 1x F-DQ. PP-PM ¹	4x F-DI(1001)/2x F-DI (1002), 2x F-DQ. PP-PM, 2x DI

1001 (One out of One):

1001 as simple redundancy, a single input connected to a fail-safe digital input

1002 (One out of Two):

Redundancy with cross-diagnosis: There are two independent sensors, each connected to an F-DI. Both sensors provide signals to the F-DI. The F-DI monitors the signals and makes decisions based on both inputs. This configuration is normally used in safety-critical applications

Vs: Integrated Sensor supply,

allows to detect short-circuit or overload scenarios, and react accordingly

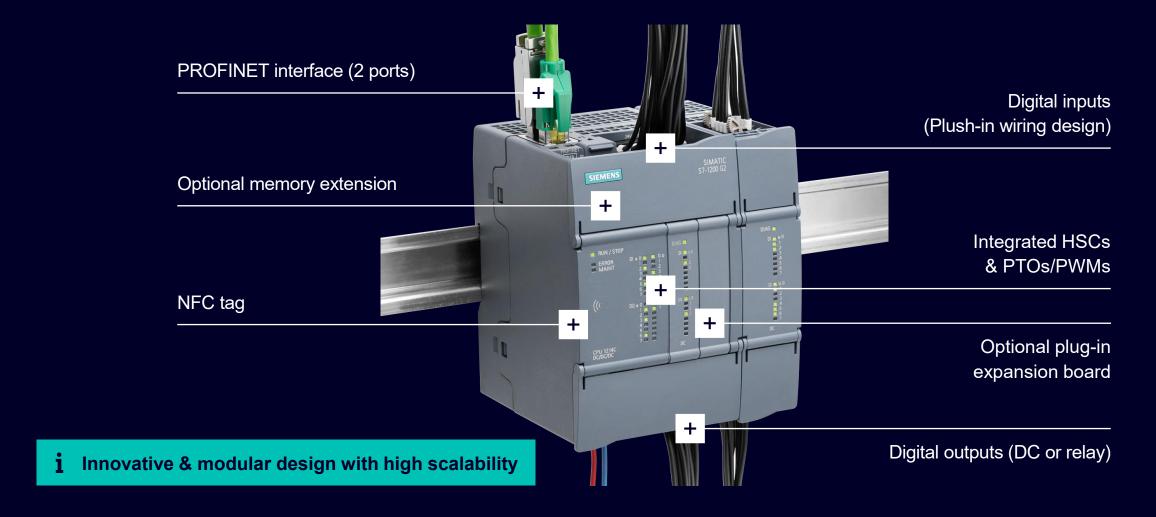


¹ Not within initial failsafe Portfolio release

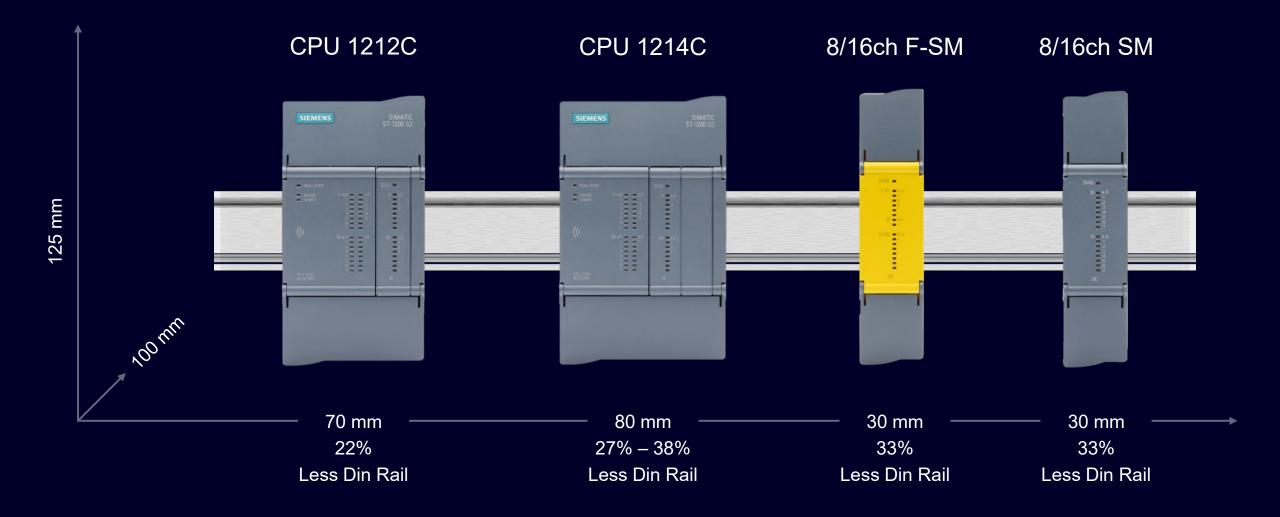


Design and handling

S7-1200 G2 CPU new hardware design



New hardware design Dimensions



Design and handling

Set-up and extension options



- Max. 1 signal board or communication board expansion
- Max. 6 signal module expansions including SM and CM
- Max. 3 communication module expansions



- Max. 2 signal board or communication board expansions
- Max. 10 signal module expansions including SM and CM
- Max. 3 communication module expansions



CPU 1212/1214

- Both communication modules and signal modules are installed to the right of the CPU
- CM must connect to the right of the CPU or to the right of another CM
- SM must connect to the right of a CPU, CM, or another SM

Variable extension and set-up options for differing requirements



Efficient motion control

Integrated motion control for basic automation machines

SIMATIC Motion Control

Supported Technology Objects (TO)¹



TO SpeedAxis



TO_CamTrack



TO_PositioningAxis



TO_MeasuringInput



TO_SynchronousAxis



TO_Cam



TO_ExternalEncoder



TO_Kinematics



TO_OutputCam

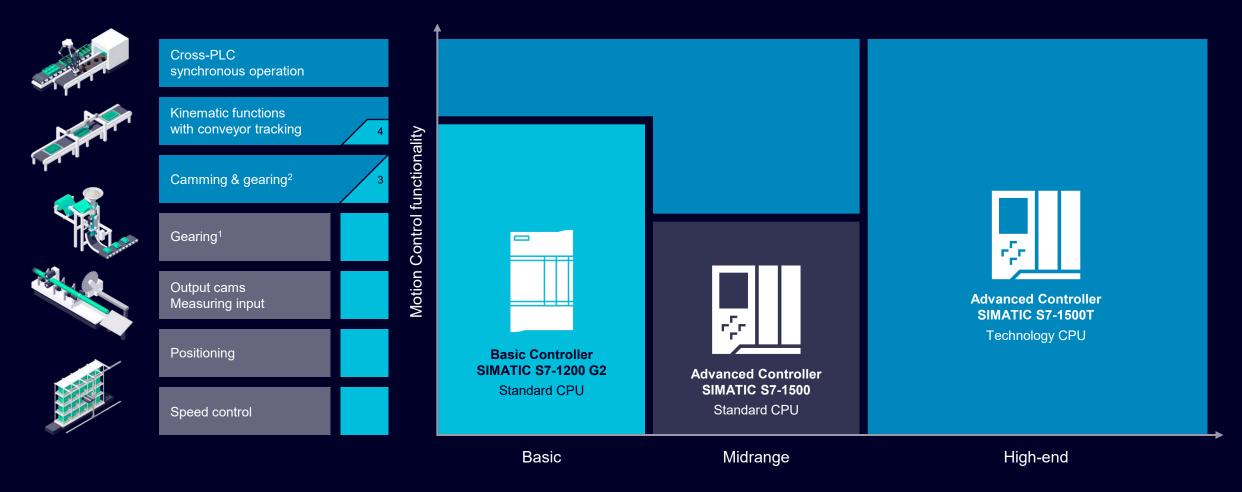
allowing to address basic motion applications



¹ Small differences in the associated instructions for some technology objects compared to S7-1500

Efficient motion control

SIMATIC S7-1200 G2 within the motion control portfolio



¹ Synchronization without specification of the synchronous position

² Synchronization with specification of the synchronous position, velocity gearing | 3 Camming with points | 4 Cartesian portal without conveyor tracking

Increased data transparency Overview NFC functionalities

S7-1200 G2 NFC	Operation	Condition						
App button		1	2	3	4	5	6	7
Allows you to view specific device information for the CPU and its connected CB/SBs and CM/SMs Devices	Device type	Read	Read	-	Read	Read	-	Read
	Article number	Read	Read		Read	Read		Read
	Hardware version	Read	Read	-	Read	Read	-	Read
	Serial number (SN)	Read	Read		Read	Read		Read
	Firmware version	Read	Read	-	Read	Read	-	Read
	Slot number	Read	Read		Read	Read		Read
	MAC address	Read	Read	-	Read	Read	-	Read
	IP address, Subnet, Gateway, PROFINET name	Read/Write	Read		Read/Write	Read		Read
	Webserver on/off	Read	Read		Read	Read		
	TIA Portal version	Read	Read		Read	Read		
	SD card info	Read	Read	-	Read	-	-	-
Allows you to read/write operations	Operation mode	Read/Write	Read	-	Read	-	_	-
Operations	Reset memory	Write	-	-	Write	-	-	-
	Set Time of Day	Write	-		Write		-	
Allows you to read diagnostics Diagnostics	Configured vs actual device diagnostics	Read	Read	-	Read	Read	-	Read
	Cycle times	Read	Read		Read		_	
	CPU memory usage	Read	Read		Read			
	Diagnostic buffer	Read	Read	_	Read	-	_	_



Condition

CPU is powered on:

- 1. Configured in STEP 7, NFC and write access enabled for the CPU
- 2. Configured in STEP 7, NFC enabled for the CPU, write access not enabled for the CPU
- 3. Configured in STEP 7, NFC is not enabled for the CPU
- 4. Not configured in STEP 7

CPU is powered off:

- 5. Configured STEP 7, NFC is enabled for the CPU
- 6. Configured in STEP 7, NFC is not enabled for the CPU
- 7. Not configured in STEP 7 configured

Fail-safe SIMATIC S7-1200 (G2): No more separate Safety license from V20 onwards STEP 7 Safety Basic will be discontinued from V20 onwards

Until TIA Portal V19

Hardware:

S7-1200 F-CPU/F-DI/F-DQ

Software:

- STEP 7 V19 Basic (or Advanced)
- STEP 7 V19 Safety Basic

Starting with TIA Portal V20



Hardware:

S7-1200 (G2) F-CPU/F-DI/F-DQ

Software:

STEP 7 V20 Basic (or Advanced)



SIMATIC S7-1200



SIMATIC S7-1200 G2



Scalable automation solutions

Scalable portfolio for standard and machine safety functions.



Seamless system integration

Seamlessly integrated in STEP 7 without need for separate license.



Reduce license costs

- Reduce entry costs
- Especially customers requiring just few F-PLCs

Hints

- V18/V19 Safety Basic licenses will still be available
- Future S7-1200 (G2) Hardware will use similar principles
- SUS contracts for Safety Basic will be discontinued end of 2024



SIMATIC S7-1200 G2

Roadmap – Summary and Outlook

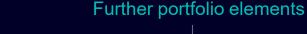
Global product announcement

Hanover Fair April 24

Initial product release with TIA Portal V20

CPUs / Power supply

- CPU 1212C
- CPU 1212FC
- CPU 1214C
- CPU 1214FC with NFC iOS app
- PM 1207



First failsafe I/O module for at least 2 safety functions



Additional safety I/Os towards the end of this year / beginning of next year



2024

2025

2026

Digital SM/SB

- SM 8DI/8DQ (+Relay)
- SM 16DI
- SM 16DQ (+Relay)
- SB 8DI, 8DQ, 4DI/4DQ

Analog SM/SB

- SM 8AI
- SM 8AQ
- SB 4AI, 4AQ, 2AI/2AQ

Further portfolio elements

First communication / temperature modules

- CM RS485 / RS232 / RS422
- CB RS485
- RTD SM 4AI
- TC: SM 8AI, SB 4AI
- CSM 1277



S7-1200 G2 additions

Wide range of additional modules and functions



Definitely the right choice

The adaptable valve terminal VTUX...



Further benefits

LightweightMade almost entirely from high-performance polymer

Cost effective Very low connection costs with or without AP communication

Easy to create valve blocks

Quick communication (real time 200 Mbaud data rate) High data rates and fast processing times

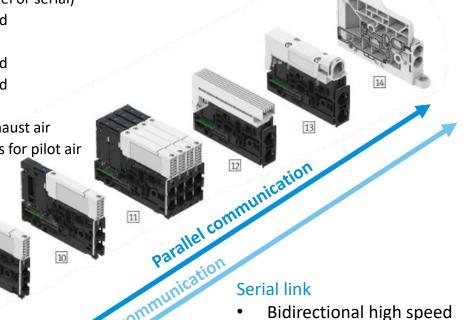
High flow rate (up to 730 l/min) Easy to configure for common applications

- Extremely flexible to use, for communication and machine concepts
- Highly modular
- All in all, it combines all the benefits of CPV, MPA and VTUG in one platform
- Open for future developments

Pneumatic components can be arranged as required

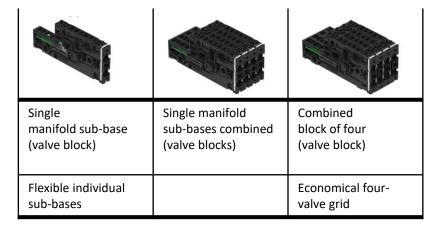
- 1. Communication interface AP-A (parallel or serial)
- 8. 4-valve manifold sub-base, 10 mm grid
- 9. Single manifold sub-base, 10 mm grid
- 10. 1-valve manifold sub-base, 12 mm grid
- 11. 4-valve manifold sub-base, 12 mm grid
- 12. Pressure supply plate with exhaust
- 13. Pressure supply plate with ducted exhaust air

14. End plate with pneumatic connections for pilot air



communication (AP inside)
Efficient direct control of up to

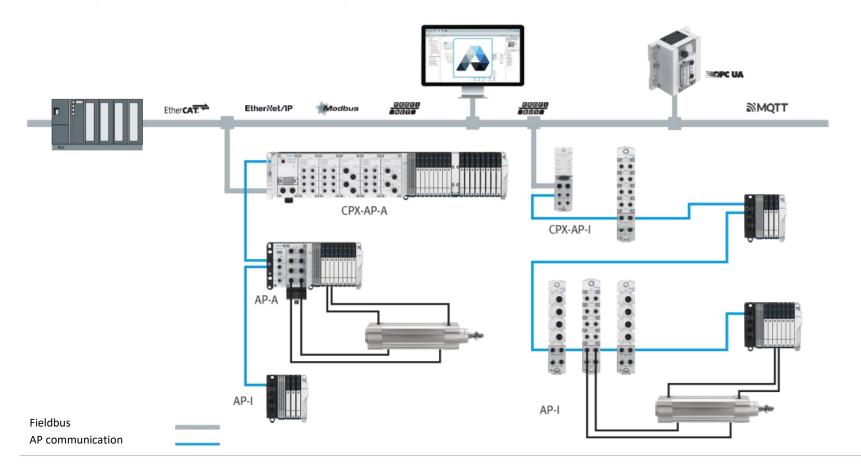
128 solenoid valves



Parallel link

Efficient direct control of up to <u>32</u>
 solenoid valves

Can be split and decentralized as required



VTUX

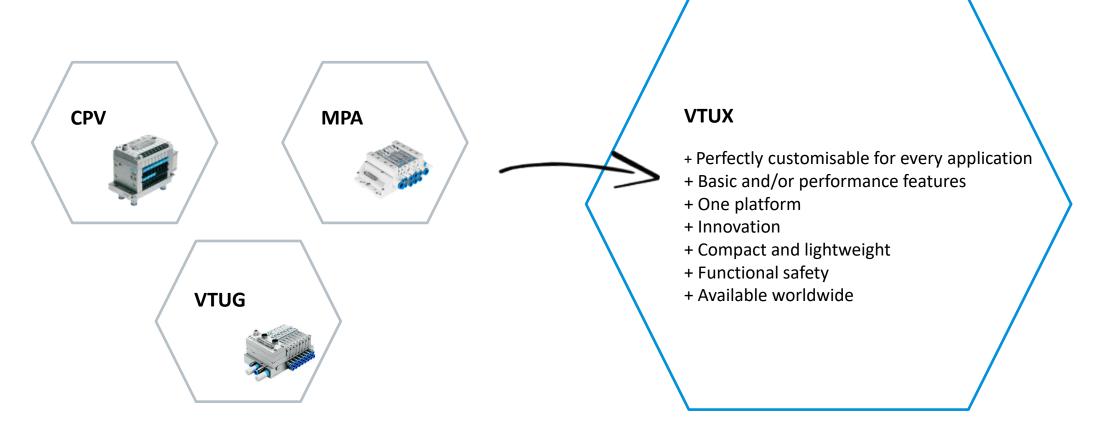
For machine architectures of all kinds:

- Centralized
- Decentralized
- Semi-centralized/ decentralized

With communication booster:

AP communication

Existing valve terminals and further development



Navigator

Aspects

Exit

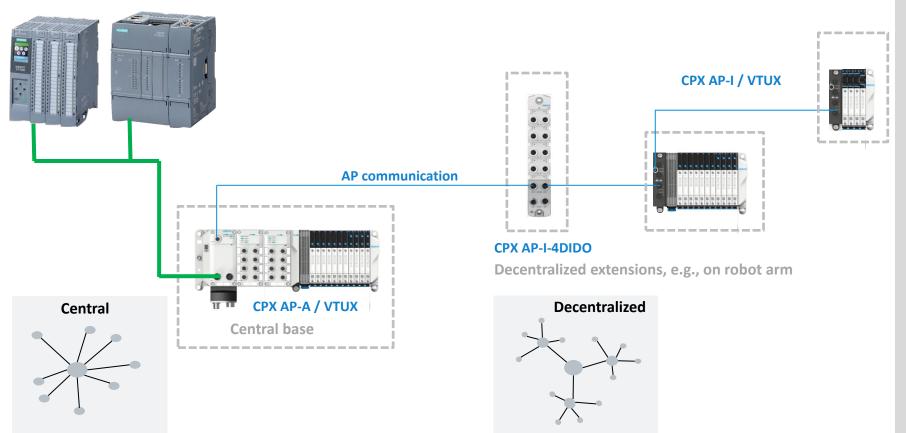
Navigator







Mixed centralized and decentralized concept



VTUX

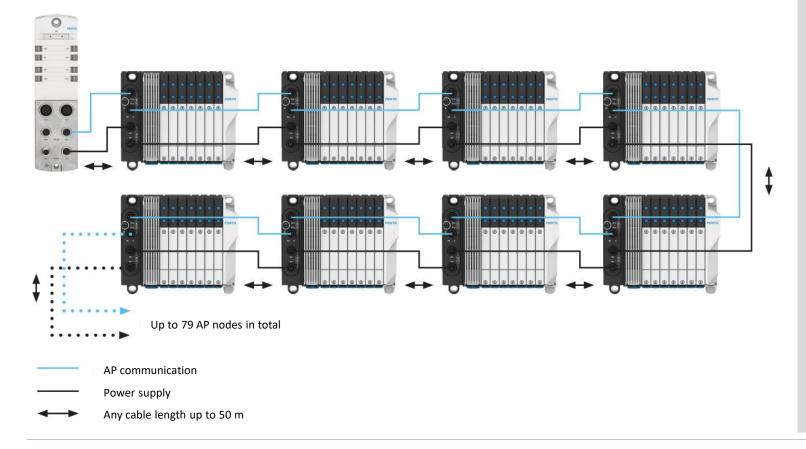
For machine architectures of all kinds:

- Centralized
- Decentralized
- Semi-centralized/ decentralized

With communication booster:

AP communication

Network parameters











Configuration options

- Up to 79 AP nodes possible
- Distances between the nodes up to 50 m
- Cost-effective communication connection
 Savings potential of up to 30% with 20 nodes
- Mains supply

Centralized: 24 V/16 A

Individual: 24 V/4 A

Navigator







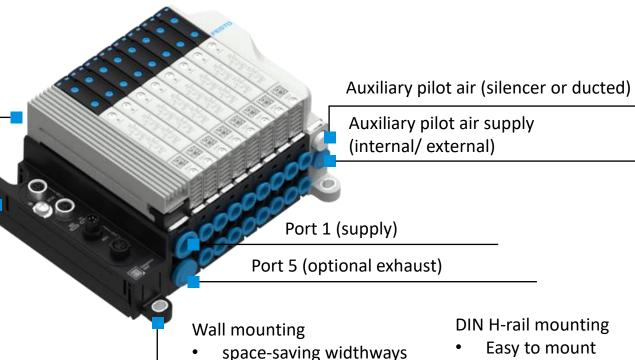
Left and right end plates

Left end plate

- Always integrated
- Replaceable silencer (no tools needed)

Electrical connection

- Saves lots of space
- Many options



Easy to mount

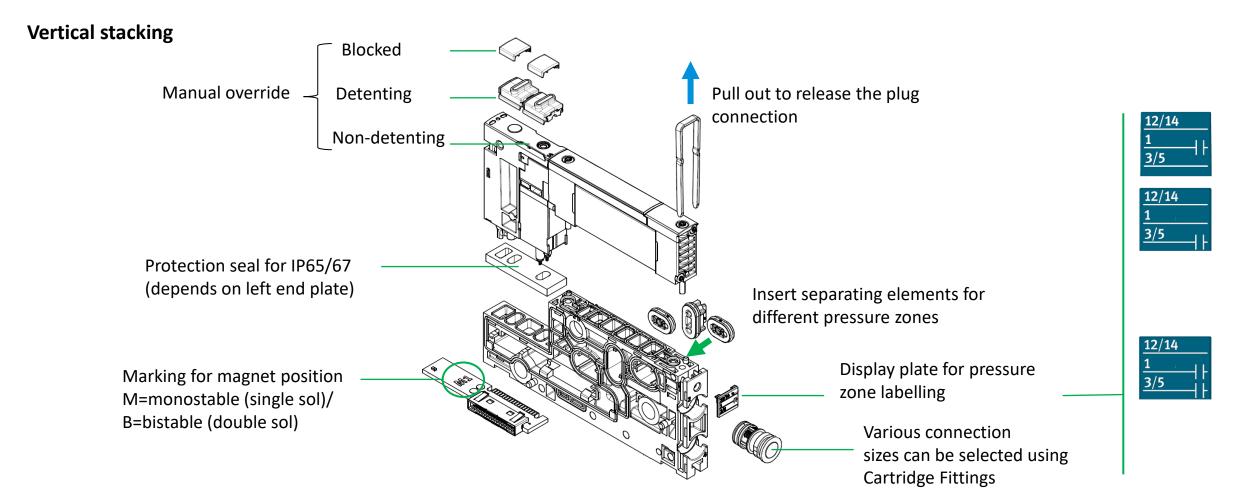


Navigator









Backbone



IO-Link

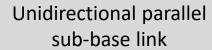
Valve terminal types

Performance



External characteristic

Blue status LEDs (AP inside, max. 128 solenoids)



External characteristic

Yellow status LEDs (max. 32 solenoids)

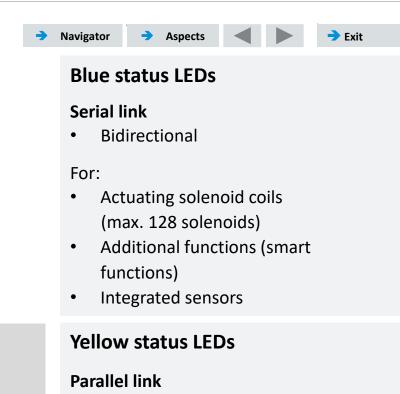


Basis



Unidirectional

Actuating solenoid coils (max. 32 solenoid coils)



Navigator







Tie rods

The manifold sub-bases are connected by a tie rod system.

This comprises a tie rods and a screw set.

The combination of tie rods and screw set is selected according to the chosen number of individual sub-bases.

Note

The tie rod system for the valve terminal VTUX consists of at least two manifold sub-bases or one manifold sub-base and one power supply module.

